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Characterising the Anisotropic Mechanical Properties of Excised Human Skin

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Abstract

The mechanical properties of skin are important for a number of applications including surgery, dermatology, impact biomechanics and forensic science. In this study we have investigated the influence of location and orientation on the deformation characteristics of 56 samples of excised human skin. Uniaxial tensile tests were carried out at a strain rate of 0.012s\(^{-1}\) on skin from the back. Digital Image Correlation was used for 2D strain measurement and a histological examination of the dermis was also performed. The mean ultimate tensile strength (UTS) was 21.6±8.4MPa, the mean failure strain 54±17%, the mean initial slope 1.18±0.88MPa, the mean elastic modulus 83.3±34.9MPa and the mean strain energy was 3.6±1.6MJ/m\(^3\). A multivariate analysis of variance has shown that these mechanical properties of skin are dependent upon the orientation of Langer lines (P<0.0001-P=0.046). The location of specimens on the back was also found to have a significant effect on the UTS (P=0.0002), the elastic modulus (P=0.001) and the strain energy (P=0.0052). The histological investigation concluded that there is a definite correlation between the orientation of Langer Lines and the preferred orientation of collagen fibres in the dermis (P<0.001). The data obtained in this study will provide essential information for those wishing to model the skin using a structural constitutive model.

Keywords: Soft tissue, Langer lines, Tensile Properties, Histology.

1 Introduction

Skin is a complex multi-layered material which can broadly be divided into three main layers, the epidermis, the dermis, and the hypodermis. The epidermis consists of cells and cellular debris, the dermis consists of mostly networks of the fibrous proteins collagen, reticulin and elastin (Wilkes et al. 1973), and the hypodermis is primarily made up of connective tissue and fat lobules. Collagen fibres account for 75% of the dry weight of dermal tissue (Wilkes et al. 1973) and it is these fibres which are responsible for the strength of the skin.

Skin is a highly non-linear, anisotropic, viscoelastic and nearly incompressible material. A typical stress-stretch graph for skin exhibits non-linear behaviour and its response is usually described as three-phase (Brown 1973). In the initial loading phase, skin is very compliant and large deformation occurs at a relatively low applied load. At this stage the fibres are largely unaligned. In the second phase the stiffness of the skin gradually increases as the fibres align themselves in
the direction of applied load. The third phase is an almost linear phase whereby the stiffness increases rapidly as the collagen fibres are mostly aligned and the overall mechanical response becomes dependent upon the mechanical properties of the collagen fibres, which are three grades of magnitude stiffer than elastin.

That skin is anisotropic was recognized as far back as the 19th century by Karl Langer (1861), who mapped the natural lines of tension which occur within the skin. These lines are identified by puncturing the skin with a circular device. The wounds then assume an elliptical shape and by joining the major axes of the ellipses a system of lines can be drawn as shown in Fig. 1(a) Orientation of samples from the back. Specimens are superimposed onto a map of the Langer lines to indicate their orientation with respect to the lines (Langer 1861). (b) Dimensions of custom made die (mm) figure 1(a). These lines are known as the Langer lines. While Langer lines are the best known skin tension lines, many variations on the original lines proposed by Langer have been made. These include the Cox lines (Cox 1941), Kraissl lines (Kraissl 1951) and Relaxed Skin Tension Lines (Borges 1984).

Early tensile tests suggested that the deformation characteristics of skin are dependent upon specimen orientation with respect to the Langer lines (Ridge & Wright 1966). More recent work conducted using Optical Coherence Elastography in-vivo, indicates a large difference between the Young moduli of skin along directions parallel and orthogonal to the Langer lines (Liang & Boppart 2010). In this study, we provide new experimental data of in-vitro human skin focusing in particular on the anisotropic properties of the skin. We also quantify the degree of anisotropy of the mechanical properties with respect to their Langer line orientation. Finally, we perform a quantitative histological analysis on the dermis of the test samples to examine a possible correlation between the orientation of Langer lines and the preferred direction of collagen fibres.

While many recent publications on skin report in-vivo experiments (Delalleau et al. 2008, Flynn et al. 2011, Moerman et al. 2009), here we have limited our experiments to in-vitro uniaxial tensile tests. As discussed by Holzapfel, there are a number of issues involved with tensile tests (Holzapfel 2006): The structural integrity of the samples may be disturbed at the lateral edges and due to the soft nature of the test material it is difficult to insert samples without subjecting them to an axial load. Despite these shortcomings, it was decided to perform in-vitro tensile tests over in-vivo testing for a number of reasons. First, in-vitro tests provide simple stress-strain relationships that can be modeled and quantified easily, since their boundary conditions are well defined. Second, for the application of this work in a further study into the dynamic rupture of skin, we are also interested
in failure and rupture of skin, and in-vitro testing makes it possible to test until failure.

Most in-vitro investigations use human skin substitutes such as pigskin, silicone or polyurethane (McCarthy et al. 2007, Gilchrist et al. 2008, Jor et al. 2011, McCarthy et al. 2010) and in-vitro tests on human skin are particularly rare. Those classical publications which do use human skin often rely on outdated equipment and their results can be difficult to interpret (Cox 1941, Jansen & Rottier 1958b). However, the development of accurate constitutive models depends heavily upon their material definitions. This study aims to provide new material data for human skin which can be applied to constitutive models in a number of technical areas such as razor blade manufacture, cosmetics, surgical simulation, forensic pathology and impact biomechanics. Uniaxial tensile tests alone are not sufficient to determine multi-dimensional material models for soft tissues and using a simple non-linear regression analysis to determine constitutive parameters may result in non-unique solutions, ill-conditioned equations and slow convergence rates. Ideally, testing of skin would involve planar biaxial tests with an in-plane shear, and separate through-thickness shear tests. While advanced testing protocols like these are not yet available, simple tension tests remain important because they serve to evaluate the level of anisotropy and to provide data which can later be used as validation for models constructed using more complicated testing methods (Holzapfel & Ogden 2009). Moreover, model parameters can be provided directly from a histological study of the collagen fibre alignment in the dermis which allows for reasonable determination of material responses (Holzapfel 2006).

2 Materials & Method

2.1 Specimen Preparation

Tensile tests and preparation were carried out in Ifsttar (Institut français des sciences et technologies des transports, de l’aménagement et des réseaux), France. French law allows human corpses that have been donated to science to be used for research purposes. The ethics committee within Ifsttar approved the use of human biological material. Skin was excised from seven subjects: three male, four female. The average age of the subjects was 89±6 years and none had any related skin diseases. Table 1 provides details on the gender and age of each subject at the time of death along with the number of days that elapsed prior to
testing.

<table>
<thead>
<tr>
<th>Gender</th>
<th>Age (years)</th>
<th>Time Elapsed*</th>
<th>Label</th>
</tr>
</thead>
<tbody>
<tr>
<td>Male</td>
<td>97</td>
<td>9</td>
<td>A</td>
</tr>
<tr>
<td>Male</td>
<td>91</td>
<td>3</td>
<td>B</td>
</tr>
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<td>97</td>
<td>2</td>
<td>C</td>
</tr>
<tr>
<td>Female</td>
<td>81</td>
<td>3</td>
<td>D</td>
</tr>
<tr>
<td>Male</td>
<td>89</td>
<td>3</td>
<td>E</td>
</tr>
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<td>Female</td>
<td>85</td>
<td>4</td>
<td>F</td>
</tr>
<tr>
<td>Female</td>
<td>86</td>
<td>4</td>
<td>G</td>
</tr>
</tbody>
</table>

Only the skin from the back of the subject was available for use. This was excised from the body with a scalpel. Each sample of skin was cut into a dogbone shape specimen, according to the ASTM D412 Standard tensile test method for vulcanised rubber, using a custom made die (see Fig. 1(a) Orientation of samples from the back. Specimens are superimposed onto a map of the Langer lines to indicate their orientation with respect to the lines (Langer 1861). (b) Dimensions of custom made die (mm)figure.1). Each specimen then had the epidermis and any underlying adipose tissue carefully removed with a scalpel. The thickness of the skin after removal of adipose tissue was measured using a Vernier Calipers and the mean thickness was 2.56±0.39mm. It was observed that skin removed from the lumbar area of the back contained more adipose tissue than skin form other areas of the back. The dimensions of the test specimens were measured before and after excision. Specimens were obtained in various orientations, shown in Fig. 1(a) Orientation of samples from the back. Specimens are superimposed onto a map of the Langer lines to indicate their orientation with respect to the lines (Langer 1861). (b) Dimensions of custom made die (mm)figure.1, to correlate the specimens with the direction of Langer lines. Each sample was grouped into one of three categories: parallel, perpendicular, or at 45° to the Langer lines. The skin was stored in moistened paper and refrigerated at 4°C until it was ready to be tested. A total of 56 samples were tested successfully. Although it is widely accepted that preconditioning is necessary at small and intermediate strains, at higher strains the stress-strain response is not significantly affected by preconditioning (Eshel 2001). The samples were therefore not pre-conditioned prior to testing.
2.2 Tensile Tests

Tensile tests were performed using a Universal Tensile Test machine. Samples were clamped using specially designed anti-slip clamps, to counteract the tendency of samples to slip in ordinary grips. The velocity of the cross-head was 50mm/min. The tensile load was measured with a 1kN piezoelectric load cell. Each tensile test was videoed with two Dalsa Falcon 1.4M100 digital video cameras at 20 frames/second. This was to record any abnormal behaviour during the experiments and also for the subsequent use of Digital Image Correlation. The gauge length and width were both measured optically. For these tests, the strain rate was 0.012s$^{-1}$, nominally the same strain rate as in tests carried out by Jansen & Rottier (1958a).

The main focus of this study is an investigation into the hyperelastic properties of skin and how these vary according to orientation and location. We thus considered the tensile tests to be taking place at quasi-static speed, and ignored viscoelastic effects for the purpose of constitutive hyperelastic modelling (for ex-
amples of studies where this route is chosen, see Jor et al. (2011), Pailler-Mattei et al. (2008), Evans & Holt (2009) or Cavicchi et al. (2009)). Further creep and stress relaxation tests, requiring additional skin samples, would need to be carried out to characterize the viscoelasticity of skin.

### 2.3 Digital Image Correlation

The stretch ratio was calculated via the displacement cell attached to the cross-head of the tensile machine. As validation, the stretch ratio was also calculated via Digital Image Correlation (DIC). DIC is a full-field optical strain measurement technique which uses image registration to measure the 2D or 3D deformation of a material. The technique works by tracking unique features on the surface of the material as it deforms. The correlations were based on images taken with the two Dalsa Falcon video cameras and processed using Vic2D Software (Version 2009-Correlated Solution, Inc.). Black spray paint was applied to the surface of the skin to create the desired random speckled pattern necessary for the correlation.

### 2.4 Histology

Three biopsies were procured from the test specimens prior to testing. These biopsies were placed in a Formaldehyde solution for fixation for a period exceeding 48 hours. Biopsies were then embedded in paraffin prior to slicing. Each biopsy was sectioned at 5µm intervals, creating a number of thin slices which were transferred onto glass slides. Biopsies were sliced in three orthogonal planes as shown in Fig. 2Biopsies of skin samples for purpose of histological staining. Note that the biopsies have been sliced in three orthogonal planes figure.2 below. The samples were then stained using a Van Gieson stain, which differentiates collagen fibres by making them appear pink/red. Images were taken of each slide using a Nikon E80i Transmission microscope and CCD camera. The orientation of collagen fibres were then calculated in a fully-automated customized MATLAB routine using the Image Processing Toolbox. The algorithm is described further in (Ni Annaidh et al. 2011).

### 2.5 Statistical Analysis

A statistical analysis of the experimental results was carried out using the General Linear Model procedure implemented in SAS 9.1 (SAS Institute Inc., USA). A
multivariate analysis of variance was utilised, followed by the Tukey-Kramer post-hoc test, to determine the influence of orientation and location of the various test samples. Significance levels for these tests were set to $P < 0.05$. When performing this test a normal distribution was assumed. To ensure our data set followed a normal distribution, a Lilliefors test was performed using the `lillietest` function in MATLAB R2007b.

3 Results

For each tensile test performed a force-displacement curve was obtained. The nominal stress was then calculated by dividing the force by the undeformed cross sectional area of the specimen. The stretch ratio was calculated by dividing the current length of the specimen by the initial length. In this way nominal stress Vs stretch ratio graphs were plotted for each specimen. A number of characteristics from these curves were identified as descriptive parameters. They are illustrated in Fig. 3 Typical stress-stretch graph for the experiments. The ultimate tensile strength is the maximum stress until failure of the specimen and is indicated by A. The elastic modulus is defined as the slope of the linear portion of the curve shown by B. The failure stretch is the maximum stretch obtained before failure and is shown by C. The initial slope is the slope of the curve at infinitesimal strains and is shown by D. The strain energy is the energy per unit volume consumed by the material during the experiment and is represented by the area under the curve figure 3.
Figure 3: Typical stress-stretch graph for the experiments. The ultimate tensile strength is the maximum stress until failure of the specimen and is indicated by A. The elastic modulus is defined as the slope of the linear portion of the curve shown by B. The failure stretch is the maximum stretch obtained before failure and is shown by C. The initial slope is the slope of the curve at infinitesimal strains and is shown by D. The strain energy is the energy per unit volume consumed by the material during the experiment and is represented by the area under the curve.

3.1 Intra-Subject and Inter-Subject Variation

A difficulty often encountered with the testing of biological tissue is the large variation in experimental results across samples. Fig. 4(a) Box and whisker plot of the intra-subject and inter-subject variation in UTS (N=56) for subjects A-G. The whiskers indicate the max and min. The boxes represent the lower and upper quartile and the line is the median. (b) Stress-Stretch response of adjacent samples from the upper back (see Fig. 1(a) Orientation of samples from the back. Specimens are superimposed onto a map of the Langer lines to indicate their orientation with respect to the lines (Langer 1861). (b) Dimensions of custom made die (mm)figure.1) with the same orientation (N=10). Colours indicate different subjects while solid and dashed lines indicate samples to the right and left of the spinal line respectively. This illustrates the inter-subject and intra-subject variation between adjacent samples with the same orientation. Figure 4(a) indicates the intra-subject and inter-subject variation in the UTS between samples. There is a large intra-subject variation for each subject which is primarily
due to anisotropy. Fig. 4(a) Box and whisker plot of the intra-subject and inter-subject variation in UTS (N=56) for subjects A-G. The whiskers indicate the max and min. The boxes represent the lower and upper quartile and the line is the median. (b) Stress-Stretch response of adjacent samples from the upper back (see Fig. 1(a) Orientation of samples from the back. Specimens are superimposed onto a map of the Langer lines to indicate their orientation with respect to the lines (Langer 1861). (b) Dimensions of custom made die (mm)figure.1) with the same orientation (N=10). Colours indicate different subjects while solid and dashed lines indicate samples to the right and left of the spinal line respectively. This illustrates the inter-subject and intra-subject variation between adjacent samples with the same orientationfigure.4(b) shows the stress-stretch graphs of ten different samples taken from five subjects. Note that the left and right samples were adjacent to one another but also in the same orientation with respect to the Langer lines. The similarity of these responses between the left and right samples from the same subjects indicates good repeatability of our experiments.

3.2 Derformation of Specimens After Excision

It is known that both shrinkage and expansion of specimens can occur upon excision from the body (Cox 1941, Jansen & Rottier 1958a, Ridge & Wright 1966, Lanir & Fung 1974). This is due to the release of residual stresses within the skin. What remains unclear is the level of residual stress present within the skin and how this may vary with the orientation of specimens. It has been suggested that the shrinkage of excised specimens is greatest in the direction of Langer lines (Ridge & Wright 1966) however our results did not corroborate this. Our results showed that 73% of all samples expanded upon excision, while only 27% of all samples shrunk. Of the samples that expanded there was a mean expansion of 5.1±3.4%. Amongst the samples that shrunk, a mean shrinkage of 3±2.9% was recorded. This is far below the reported maximum figure of 20% shrinkage for human skin (Jansen & Rottier 1958a) and 40% shrinkage provided for pig skin (Jor et al. 2011).

3.3 Histology

The collagen fibres were assumed to form an interweaving lattice structure, as first postulated by Ridge & Wright (1966). Here, the preferred orientation is defined as the mean of the orientations of two families of interweaving fibres. It was assumed that the collagen fibres are distributed according to a transversely isotropic
Figure 4: (a) Box and whisker plot of the intra-subject and inter-subject variation in UTS (N=56) for subjects A-G. The whiskers indicate the max and min. The boxes represent the lower and upper quartile and the line is the median. (b) Stress-Stretch response of adjacent samples from the upper back (see Fig. 1(a) Orientation of samples from the back. Specimens are superimposed onto a map of the Langer lines to indicate their orientation with respect to the lines (Langer 1861). (b) Dimensions of custom made die (mm) with the same orientation (N=10). Colours indicate different subjects while solid and dashed lines indicate samples to the right and left of the spinal line respectively. This illustrates the inter-subject and intra-subject variation between adjacent samples with the same orientation.

and π-periodic Von Mises distribution. The Von Mises distribution is commonly assumed for directional data. The standard π-periodic Von Mises Distribution is normalized and the resulting distribution is given as follows.

$$
\rho(\Theta) = 4 \sqrt{\frac{b}{2\pi}} \frac{\exp[b(\cos(2\Theta) + 1)]}{\text{erf}i\sqrt{2b}}
$$

where $\Theta$ is the mean orientation of fibres and $b$ is the concentration parameter associated with the Von Mises distribution. The parameter $b$ was evaluated by the approximation given by Fisher (1993) using the CircStat package available on the MATLAB file exchange (Berens 2009).

Table 2 Mean orientation of collagen fibres and their Langer Line orientations. (Note that the data given is axial data i.e. it represents undirected lines and does
not distinguish between $\theta$ and $\pi + \theta$ (Jones 2006) e.g. the orientation of $0^\circ$ and $180^\circ$ are equivalent). Table 2 shows the calculated concentration parameter $b$, the mean orientation of collagen fibres and the orientation with respect to Langer lines. A Pearson correlation test was carried out to test for a correlation between the measured preferred orientation obtained through histology and the perceived orientation of Langer lines. The correlation was deemed to be significant ($P < 0.001$) with a Pearson $R$ value of $0.9487$ and an $R^2$ value of $0.9000$.

Table 2: Mean orientation of collagen fibres and their Langer Line orientations. (Note that the data given is axial data i.e. it represents undirected lines and does not distinguish between $\theta$ and $\pi + \theta$ (Jones 2006) e.g. the orientation of $0^\circ$ and $180^\circ$ are equivalent).

<table>
<thead>
<tr>
<th>Orientation with respect to Langer Lines</th>
<th>Preferred Orientation, $\Theta$</th>
<th>Level of dispersion, $b$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$0^\circ$</td>
<td>$40^\circ$</td>
<td>$0.5222$</td>
</tr>
<tr>
<td>$0^\circ$</td>
<td>$163^\circ$</td>
<td>$1.1605$</td>
</tr>
<tr>
<td>$0^\circ$</td>
<td>$16^\circ$</td>
<td>$1.1471$</td>
</tr>
<tr>
<td>$0^\circ$</td>
<td>$168^\circ$</td>
<td>$0.6004$</td>
</tr>
<tr>
<td>$45^\circ$</td>
<td>$40^\circ$</td>
<td>$0.8388$</td>
</tr>
<tr>
<td>$45^\circ$</td>
<td>$61^\circ$</td>
<td>$0.7926$</td>
</tr>
<tr>
<td>$45^\circ$</td>
<td>$46^\circ$</td>
<td>$0.7453$</td>
</tr>
<tr>
<td>$45^\circ$</td>
<td>$53^\circ$</td>
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<td>$0.8326$</td>
</tr>
<tr>
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<td>$0.9330$</td>
</tr>
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<td>$90^\circ$</td>
<td>$73^\circ$</td>
<td>$0.9007$</td>
</tr>
<tr>
<td>$90^\circ$</td>
<td>$120^\circ$</td>
<td>$0.6197$</td>
</tr>
</tbody>
</table>

### 3.4 Influence of Orientation

Specimens were analysed by considering their orientation with respect to the Langer lines (parallel, perpendicular or at $45^\circ$ to the Langer lines, see Fig. 1(a) Orientation of samples from the back. Specimens are superimposed onto a map of the Langer lines to indicate their orientation with respect to the lines (Langer 1861). (b) Dimensions of custom made die (mm)figure.1). A multiway analysis of variance found the orientation of Langer lines to have a significant effect on the
3.5 Influence of Location

When results were grouped into three locations (Upper Back, Middle Back and Lower Back, see Fig. 1(a) Orientation of samples from the back. Specimens are superimposed onto a map of the Langer lines to indicate their orientation with respect to the lines (Langer 1861). (b) Dimensions of custom made die (mm)figure.1), a multiway analysis of variance also found the location of specimens to have a significant effect on the UTS ($P=0.0002$), the strain energy ($P=0.0002$)
Table 3: Mean ± standard deviation for each orientation/location group.

<table>
<thead>
<tr>
<th>Langer Line Orientation</th>
<th>Location</th>
<th>N</th>
<th>UTS (MPa)</th>
<th>Strain Energy (MJ/m³)</th>
<th>Failure Stretch</th>
<th>Elastic Modulus (MPa)</th>
<th>Initial Slope (MPa)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parallel</td>
<td>Middle</td>
<td>9</td>
<td>28.64 ± 9.03</td>
<td>4.28 ± 1.49</td>
<td>1.46 ± 0.07</td>
<td>112.47 ± 36.49</td>
<td>1.21 ± 0.97</td>
</tr>
<tr>
<td></td>
<td>Bottom</td>
<td>7</td>
<td>17.60 ± 4.77</td>
<td>2.54 ± 0.76</td>
<td>1.74 ± 0.32</td>
<td>73.81 ± 19.41</td>
<td>1.95 ± 1.34</td>
</tr>
<tr>
<td>45°</td>
<td>Top</td>
<td>12</td>
<td>22.7 ± 3.61</td>
<td>3.80 ± 0.92</td>
<td>1.52 ± 0.10</td>
<td>82.62 ± 17.36</td>
<td>0.99 ± 0.51</td>
</tr>
<tr>
<td>45°</td>
<td>Middle</td>
<td>9</td>
<td>28.85 ± 7.87</td>
<td>5.38 ± 2.59</td>
<td>1.52 ± 0.15</td>
<td>103.49 ± 41.20</td>
<td>1.33 ± 0.96</td>
</tr>
<tr>
<td>45°</td>
<td>Bottom</td>
<td>5</td>
<td>20.23 ± 4.18</td>
<td>3.31 ± 0.67</td>
<td>1.43 ± 0.04</td>
<td>82.81 ± 18.43</td>
<td>1.30 ± 0.60</td>
</tr>
<tr>
<td>Perpendicular</td>
<td>Middle</td>
<td>9</td>
<td>16.53 ± 5.71</td>
<td>2.98 ± 0.89</td>
<td>1.52 ± 0.08</td>
<td>63.75 ± 24.59</td>
<td>0.91 ± 0.68</td>
</tr>
<tr>
<td>Perpendicular</td>
<td>Bottom</td>
<td>5</td>
<td>10.56 ± 8.41</td>
<td>2.44 ± 1.04</td>
<td>1.61 ± 0.14</td>
<td>37.66 ± 36.41</td>
<td>0.54 ± 0.33</td>
</tr>
</tbody>
</table>

and the Elastic Modulus (P=0.001), but neither on the failure stretch nor the initial slope. Fig. 6 Influence of location on back on the elastic modulus, strain energy and UTS. Values given include mean and standard deviations. Figure 6 displays variations in the mechanical properties between different locations on the back for the three properties which showed a significant effect i.e., the elastic modulus, UTS and strain energy. Note that there was no significant effect noted for either the initial slope or the failure stretch.

3.6 Digital Image Correlation

An important feature of DIC is its ability to calculate local strains throughout the plane of the test specimens. Fig. 7(a) Comparison of stretch measurement from DIC and DS over the length of the specimen throughout the duration of a given tensile test. (b) Distribution of local Lagrangian strains just before rupture. Note the area of localised magnification in red. This is the location where rupture subsequently occurred. Figure 7(a) shows a comparison between the local stretch values, obtained through DIC, and the overall stretch values, obtained from the displacement sensor (DS), throughout the duration of a test. It can be seen that
there is good agreement for most of the duration of the test. However, upon closer inspection it was found that a local magnification of the stretch ratio occurred just before rupture, close to the rupture site (for magnitudes, see Table 4). Local magnification of the stretch ratio occurs just before rupture (for magnitudes, see Table 4). Fig. 7(a) Comparison of stretch measurement from DIC and DS over the length of the specimen throughout the duration of a given tensile test. (b) Distribution of local Lagrangian strains just before rupture. Note the area of localised magnification in red. This is the location where rupture subsequently occurred. Fig. 7(b) shows the distribution of strains throughout the sample for a frame just before rupture. For some samples this magnification was very localised while for others it was distributed over a larger area. A similar result was reported by Jacquemoud et al. (2007) who found that at the rupture site, the local strain values can be up to twice as large as what is measured using overall specimen strains calculated over the entire length of a specimen.
Figure 7: (a) Comparison of stretch measurement from DIC and DS over the length of the specimen throughout the duration of a given tensile test. (b) Distribution of local Lagrangian strains just before rupture. Note the area of localised magnification in red. This is the location where rupture subsequently occurred.

Table 4: Local and overall maximum stretch ratios for five different samples. Local magnification of the stretch ratio occurs just before rupture.

<table>
<thead>
<tr>
<th>Sample</th>
<th>Local Max Stretch Ratio</th>
<th>Overall Specimen Stretch Ratio</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1.47</td>
<td>1.38</td>
</tr>
<tr>
<td>2</td>
<td>1.45</td>
<td>1.40</td>
</tr>
<tr>
<td>3</td>
<td>1.65</td>
<td>1.45</td>
</tr>
<tr>
<td>4</td>
<td>1.70</td>
<td>1.48</td>
</tr>
<tr>
<td>5</td>
<td>1.70</td>
<td>1.50</td>
</tr>
</tbody>
</table>

4 Discussion

When comparing our own data to that in the literature it can be seen that there is much variation between authors. This is to be expected for biological tissues. First, because of the biological variability between subjects; second, because of the anisotropic nature of skin itself; and third, because of the sensitivity of biological tissues to test conditions. In the absence of extensive published litera-
ture on the properties of in vitro human skin from the back. Table 5 compares results obtained to results in the literature. All experiments were carried out in-vitro on excised human skin. Results are displayed as means (± standard deviation) and range. Table 5 compares results obtained from the literature from a range of locations and test methods to our own results. The mean ultimate tensile strength was 21.6±8.4MPa, the mean failure strain 54±17%, the mean initial slope 1.18±0.88MPa, the mean elastic modulus 83.3±34.9MPa and the mean strain energy was 3.6±1.6MJ/m$^3$. It can be seen that our experimental results fall within the ranges found in the literature for in-vitro tests. However there is a large variation with the various types of in-vivo tests. The reasons for this difference has been widely discussed and the primary causes are due to the properties of skin changing once removed from the body; the different testing methods employed; and an inability to establish boundary conditions and to isolate the skin’s behaviour from its surrounding tissue in vivo. Furthermore, the 'Modulus' defined in-vivo is in the low-strain range, whereas the Modulus calculated here is in the high-strain range. The in-vivo modulus then, should be compared with the Initial slope, rather than the elastic modulus.

It has been well documented over the years that the deformation characteristics of skin are dependent upon specimen orientation, but few authors describe the level of anisotropy involved in much detail. In this study, we have provided statistical information on the effect of Langer line orientation on the UTS, strain energy, failure strain, initial slope, and elastic modulus. We have been unable to establish a link between the level of shrinkage of skin upon excision and the orientation of the Langer lines. Instead we found that the majority of samples actually expanded upon excision. The reason for this discrepancy may be two-fold; firstly, the skin has been excised from the back, not the abdomen, which may be more extensible to accommodate the shrinkage and expansion of the stomach. Secondly, the skin samples were excised from elderly subjects which naturally exhibit less extensibility. This has been previously noted by Jansen & Rottier (1958a,b) who stated that skin excised from elderly subjects was more likely to expand rather than retract, when compared to younger subjects. Finally, the authors noted that while shrinkage of the skin may have occurred directly after excision from the body, after subcutaneous fat was removed, the samples often expanded. This poses the question what effect the subcutaneous fat has on the level of shrinkage/ expansion in the skin, usually thought to be solely due to the release of residual stresses in the skin.

Previous studies show that the properties of skin are dependent upon specimen location (Haut 1989, Sugihara et al. 1991). Our results also indicate that the
Table 5: Comparison of results obtained to results in the literature. All experiments were carried out in-vitro on excised human skin. Results are displayed as means (±standard deviation) and ranges.

<table>
<thead>
<tr>
<th>Author</th>
<th>Test type</th>
<th>UTS (MPa)</th>
<th>Failure Strain %</th>
<th>Elastic Modulus MPa</th>
<th>Initial Slope MPa</th>
<th>Site*</th>
<th>Age</th>
</tr>
</thead>
<tbody>
<tr>
<td>(Jansen &amp; Rottier 1958b)</td>
<td>in vitro tension</td>
<td>1-24</td>
<td>17-207</td>
<td>2.9-54.0</td>
<td>0.69-3.7</td>
<td>Ab</td>
<td>0-99</td>
</tr>
<tr>
<td>(Dunn &amp; Silver 1983)</td>
<td>in vitro tension</td>
<td>2-15</td>
<td></td>
<td>18.8</td>
<td>0.1</td>
<td>AB&amp;T</td>
<td>47-86</td>
</tr>
<tr>
<td>(Vogel 1987)</td>
<td>in vitro tension</td>
<td>5-32</td>
<td>30-115</td>
<td>15-150</td>
<td></td>
<td>V</td>
<td>0-90</td>
</tr>
<tr>
<td>(Jacque-moud et al. 2007)</td>
<td>in vitro tension</td>
<td>5.7-12.6</td>
<td>27-59</td>
<td>19.5-87.1</td>
<td></td>
<td>F &amp; A</td>
<td>62-98</td>
</tr>
<tr>
<td>(Agache et al. 1980)</td>
<td>in vivo torsion</td>
<td>0.42-0.85</td>
<td></td>
<td></td>
<td></td>
<td>Back</td>
<td>3-89</td>
</tr>
<tr>
<td>(Diridollou et al. 1998)</td>
<td>in vivo suction</td>
<td>0.12-0.25</td>
<td></td>
<td></td>
<td></td>
<td>A &amp; F</td>
<td>20-30</td>
</tr>
<tr>
<td>(Khatyr et al. 2004)</td>
<td>in vivo tension</td>
<td>0.13-0.66</td>
<td></td>
<td></td>
<td></td>
<td>Tibia</td>
<td>22-68</td>
</tr>
<tr>
<td>(Pailler-Mattei et al. 2008)</td>
<td>in vivo indentation</td>
<td>0.0045-0.008</td>
<td></td>
<td></td>
<td></td>
<td>A</td>
<td>30</td>
</tr>
<tr>
<td>(Zahouani et al. 2009)</td>
<td>in vivo indentation &amp; static friction</td>
<td>0.0062-0.0021</td>
<td></td>
<td></td>
<td></td>
<td>A</td>
<td>55-70</td>
</tr>
<tr>
<td>Our results</td>
<td>in vitro tensile</td>
<td>21.6 ±8.4</td>
<td>54 ±17</td>
<td>83.3 ±34.9</td>
<td>1.18 ±0.88</td>
<td>Back</td>
<td>81-97</td>
</tr>
</tbody>
</table>

*Ab = abdomen, T = thorax, V = various, F = forehead, A = arm

UTS, strain energy and elastic modulus vary depending on location. However, as only skin from the back was available for testing, the location of specimens could only be categorised into upper back, middle back and lower back regions. It was
nonetheless advantageous to gain information on skin from the back because it is
seldom as readily available as that from the abdominal area.

All subjects were between the ages of 81 and 97. This meant that no compar-
isons based on the age of subjects could be performed. Numerous other studies
have investigated the influence of age on the structure and mechanical behaviour
of skin (Vogel 1987, Haut 1989, Sugihara et al. 1991). It has been established that
progressive straightening of elastin fibres occurs over time (Lavker et al. 1987).
This may cause the shortened phase I region of the stress-strain curve leading to
an overall reduction in extensibility. The slope of the phase III portion of the
curve however remains relatively constant (Wilkes et al. 1973). Nonetheless, it
must be highlighted that the results of this study may not reflect the behaviour
of younger skin and consideration must be taken to allow for age-related effects
when interpreting these results.

A number of days had elapsed between the time of death and testing (see Ta-
ble 1 Information on each test subject. ∗Number of days elapsed after death prior
to testing table 1) but it has been previously demonstrated that skin samples can be
refrigerated for up to 48 hours under the right conditions with no discernible ef-
effects on the mechanical properties (Daly 1982) and for up to 21 days for thoracic
aortas under certain conditions (Adham et al. 1996).

DIC is a common strain measurement technique in biomechanics, however
until now it has been used mostly for in-vivo experiments or at low strains (Moer-
man et al. 2009). The results yielded from the present use of DIC may be useful in
the future as validation for a finite element approach. Also the reported local max-
imum strain values are of interest to those wishing to model failure of biological
tissues.

In this paper, our data has been examined with respect to the perceived ori-
entation of Langer lines. However, the Langer lines are known to vary with location,
age and gender and no universal pattern of maximum tensions exist (Brown 1973).
The orientation of the Langer lines cannot be identified with certainty unless the
skin of a whole cadaver is punctured, an option which was not feasible for this
study. Given the importance of the Langer lines on the mechanical properties of
skin there is a need for patient-specific maps to be established in-vivo and in real
time. These could be produced by relying on sophisticated imaging techniques
such as those produced by ultrasonic surface wave propagation or optical coher-
ence tomography and may eventually have applications in cosmetic surgery.

Cox (1941) and Stark (1977) both illustrated that the orientations of Langer
lines remain even after the skin is removed from the body and the skin tension re-
leased, and concluded that the lines have an anatomical basis. However it remains
unclear in the literature whether the Langer lines have a structural basis, and to the authors’ knowledge there is no quantitative data published on this point. By identifying the orientation of collagen fibres in the dermis we have shown that there is a correlation between their orientation and that of the Langer Lines. However, it is only when a quantitative study is performed that this becomes apparent.

Knowledge of the collagen fibre orientation along with the presented stress-strain data will also facilitate the determination of material parameters for structurally based constitutive models for skin. While the test method described here is not sufficient to fully describe the full 3-D response of the material, Holzapfel (2006) has shown how a combination of tensile tests and histological data can be used to reasonably determine the material parameters of a 3D hyperelastic model. In a companion paper (Ní Annaidh et al. 2011), we use a similar approach in order to determine the material and structural parameters of a suitable anisotropic model, the so-called Gasser-Ogden-Holzapfel model (Gasser et al. 2006), readily implemented into the commercial Finite Element code ABAQUS.

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